



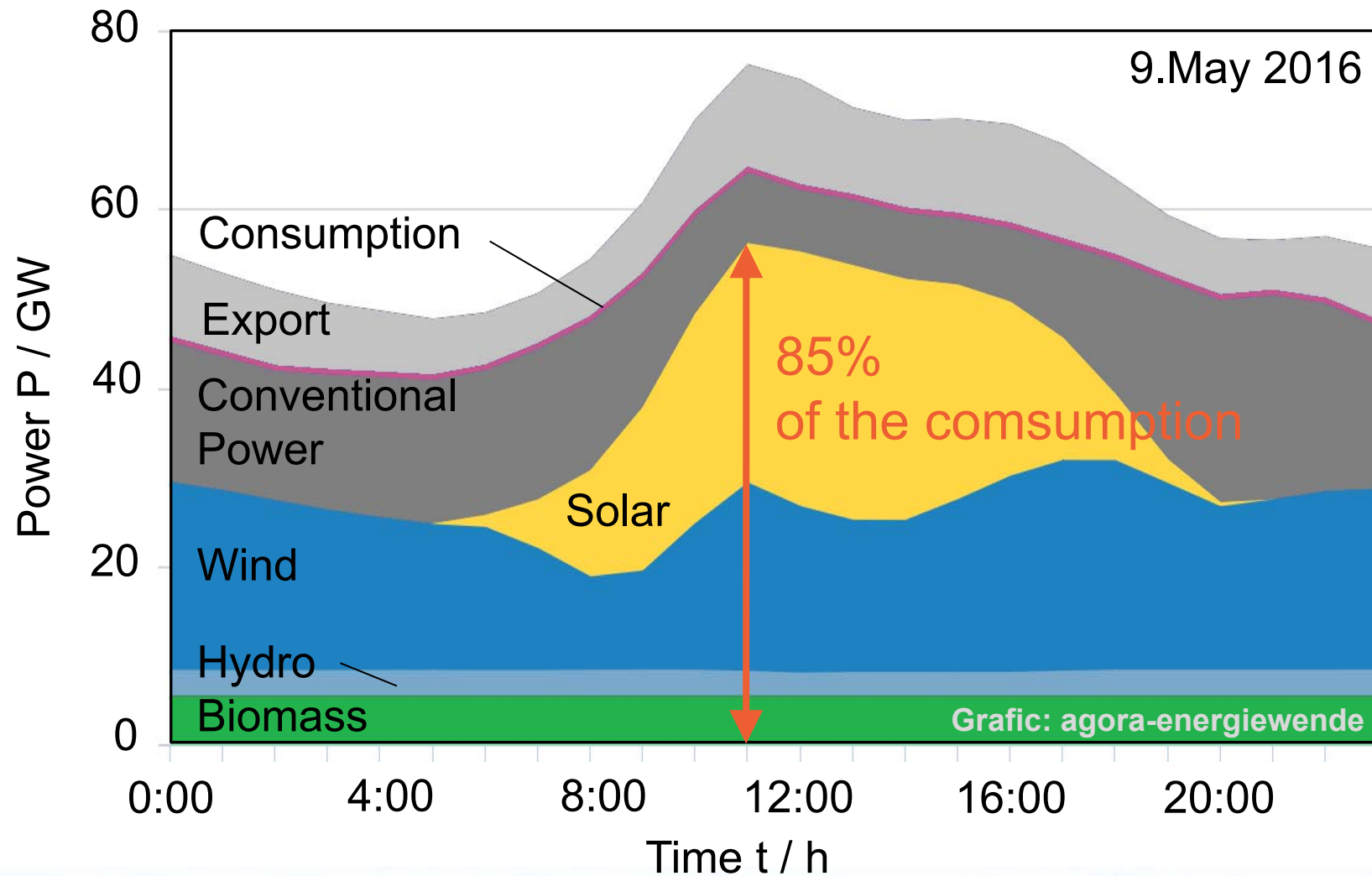
# Decentralized grid control

Prof. Dr. Eberhard Waffenschmidt

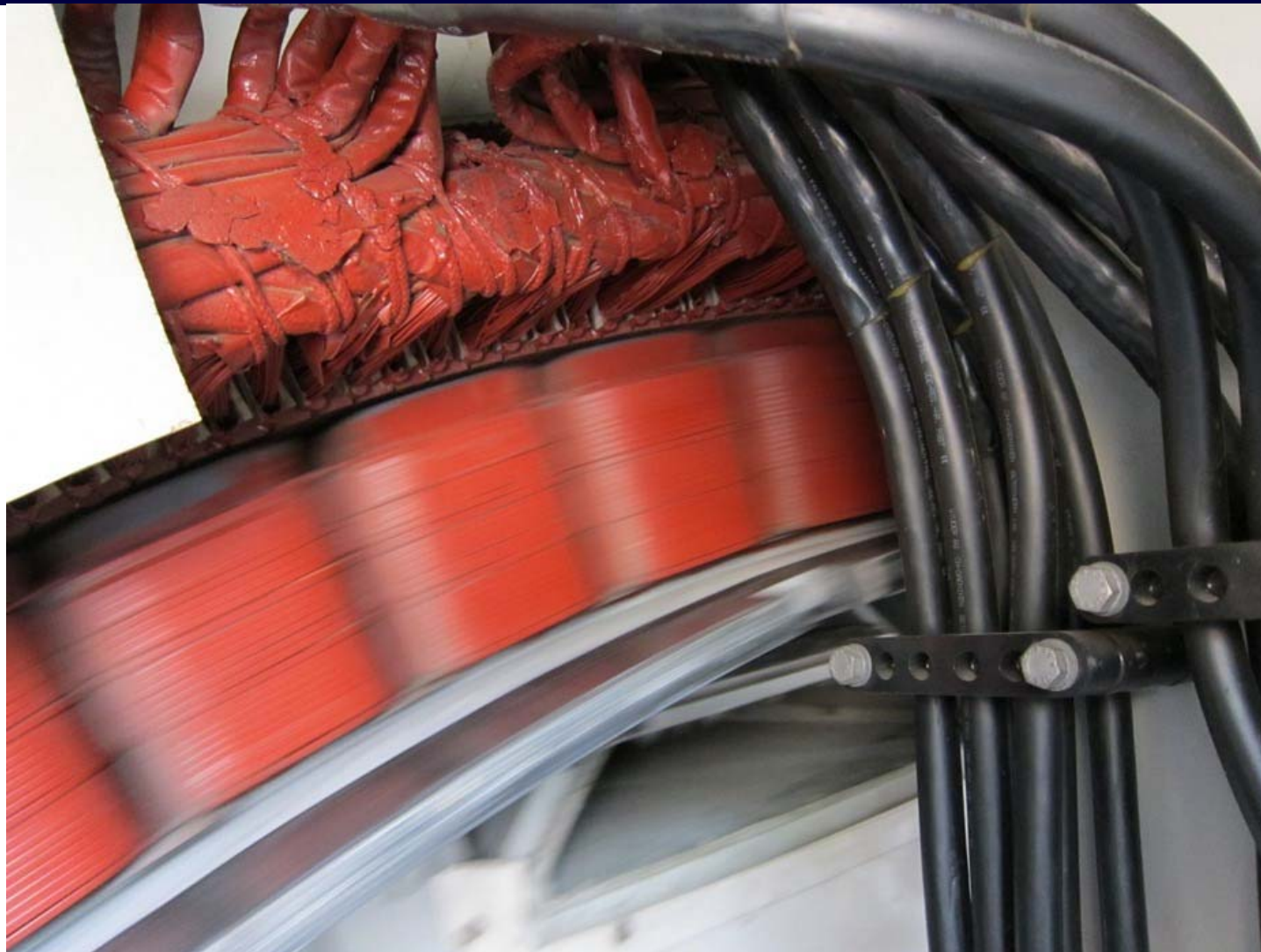
May 2016

IRENEC 2016, Istanbul

# Sometimes 85% RE in the grid



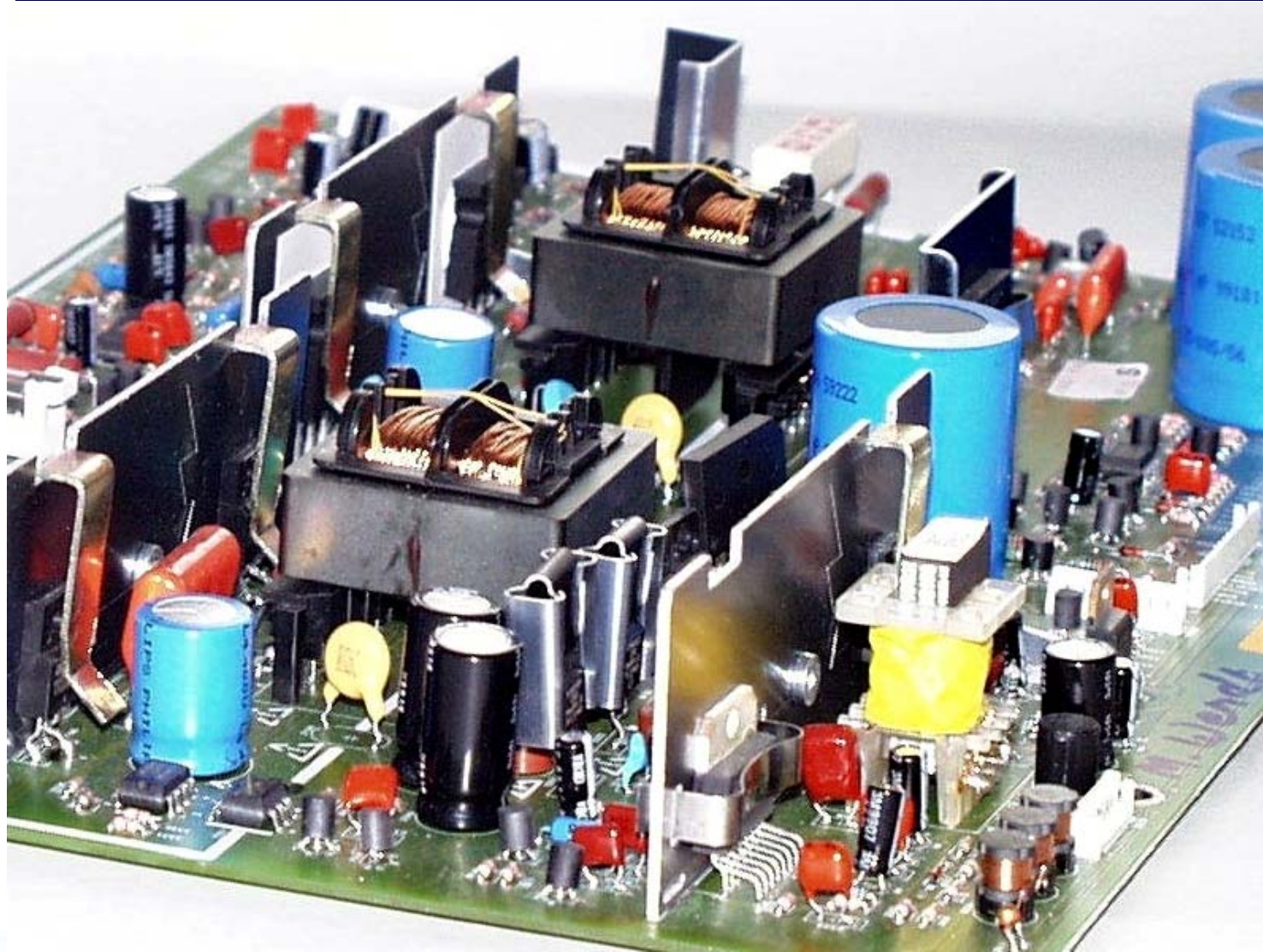
# Conventional generators will be missing





# Generators replaced by electronics

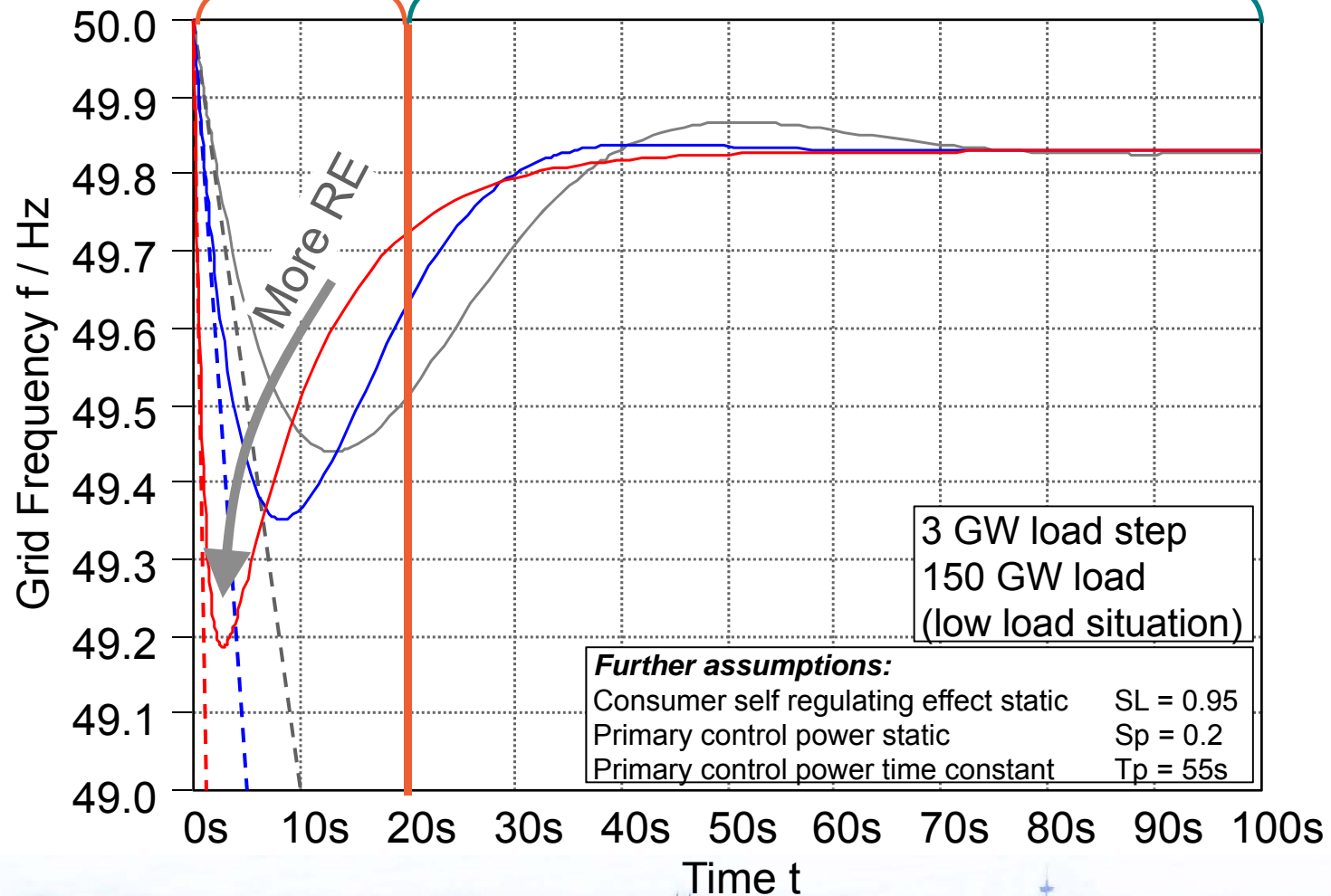
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# Reaction to load step

Instantaneous reaction:  
*Virtual inertia with power  
inverters*

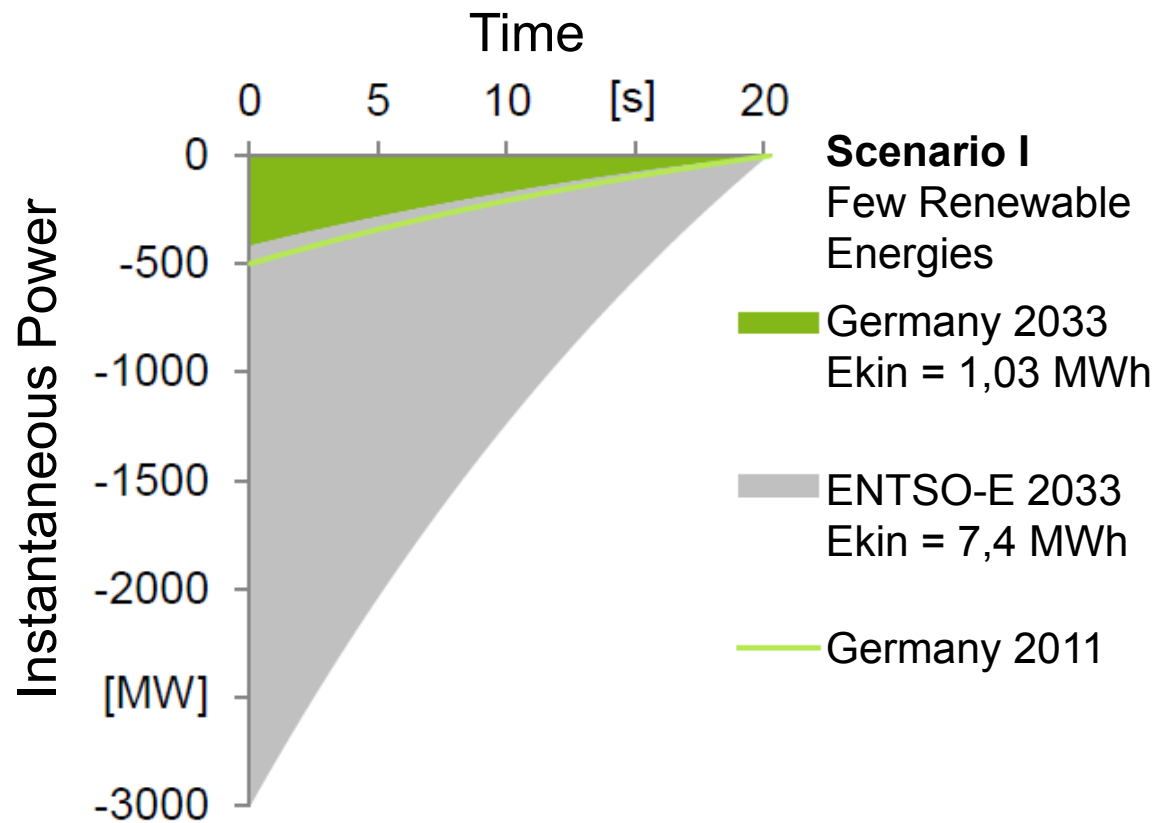
Primary control:  
*Use of batteries*



# Virtual inertia with power converters



# Required Energy



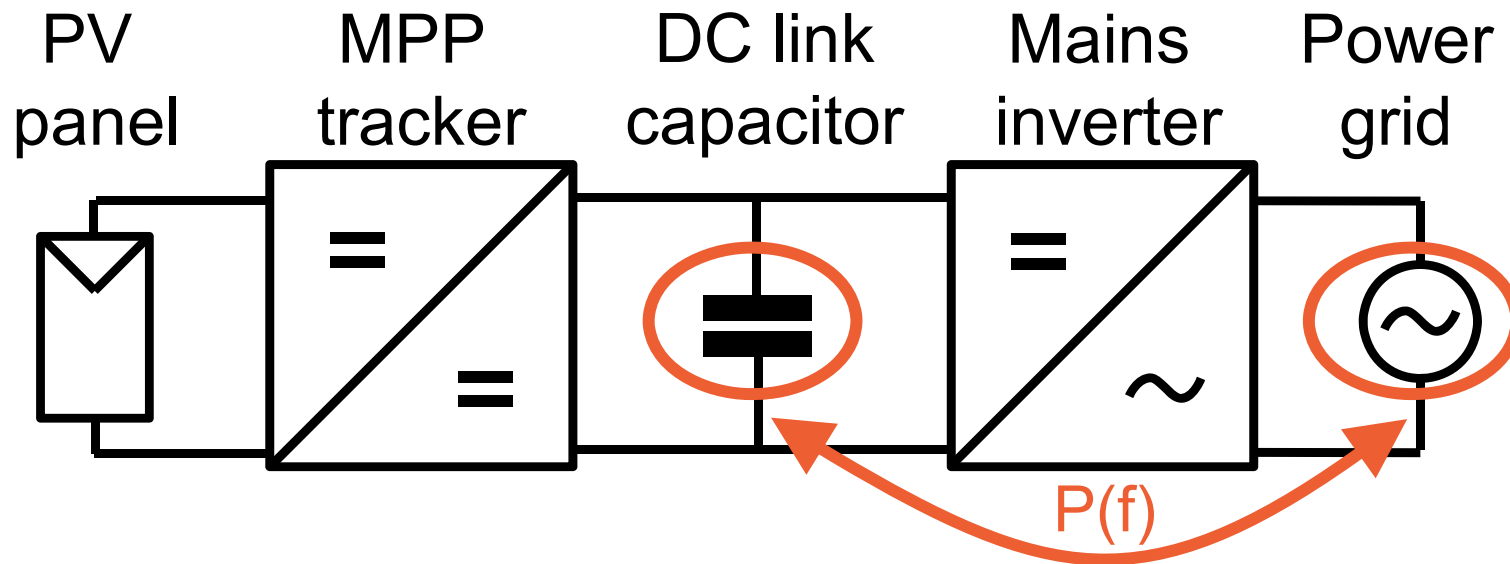
## ■ Contribution of Germany to Instantaneous Control:

- Energy: 3700 MWs
- Power: 372 MW

## ■ With feed in of 80 GW:

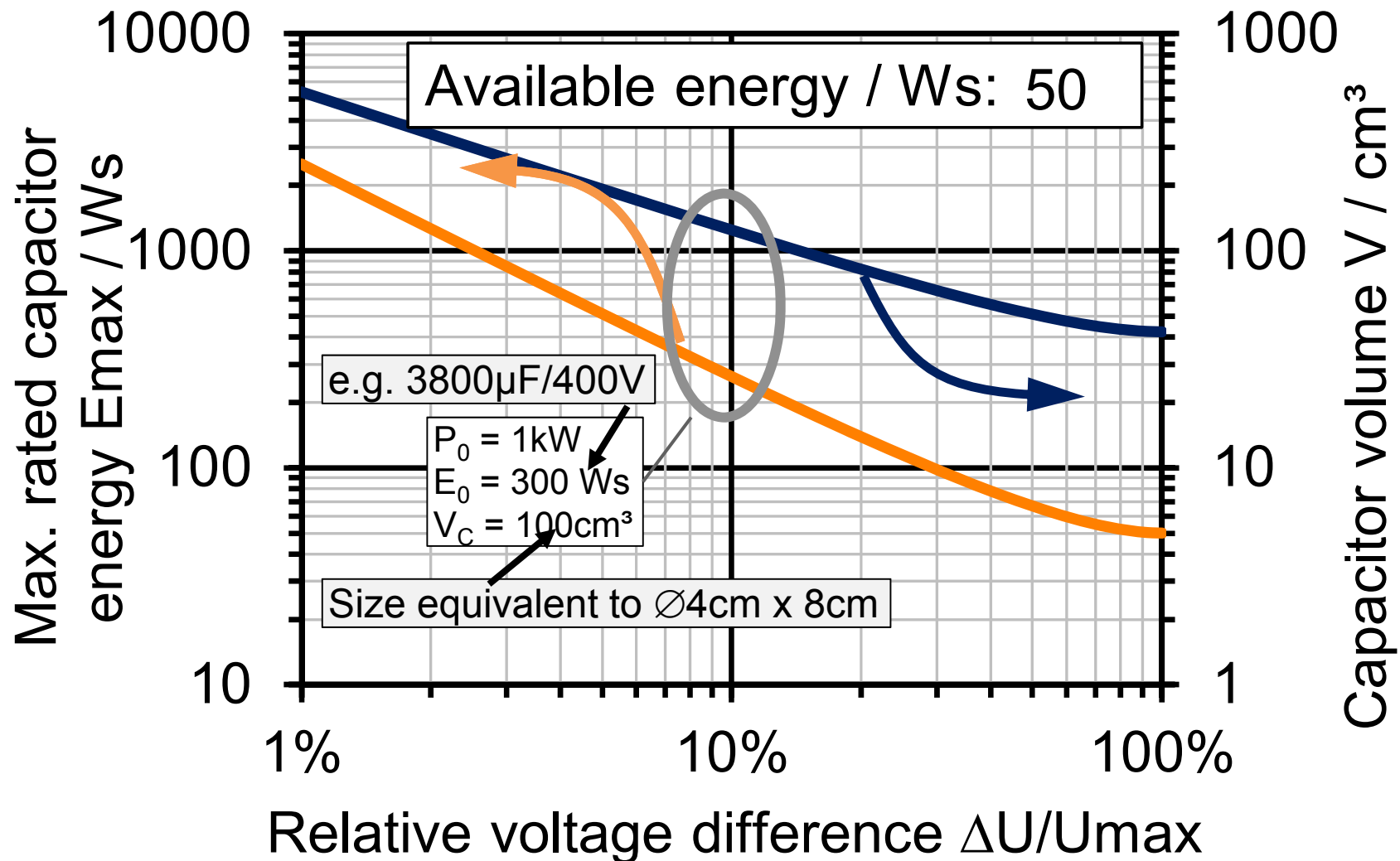
- Power: 5W / kW
- Energy: 50Ws / kW

# Topology for virtual inertia

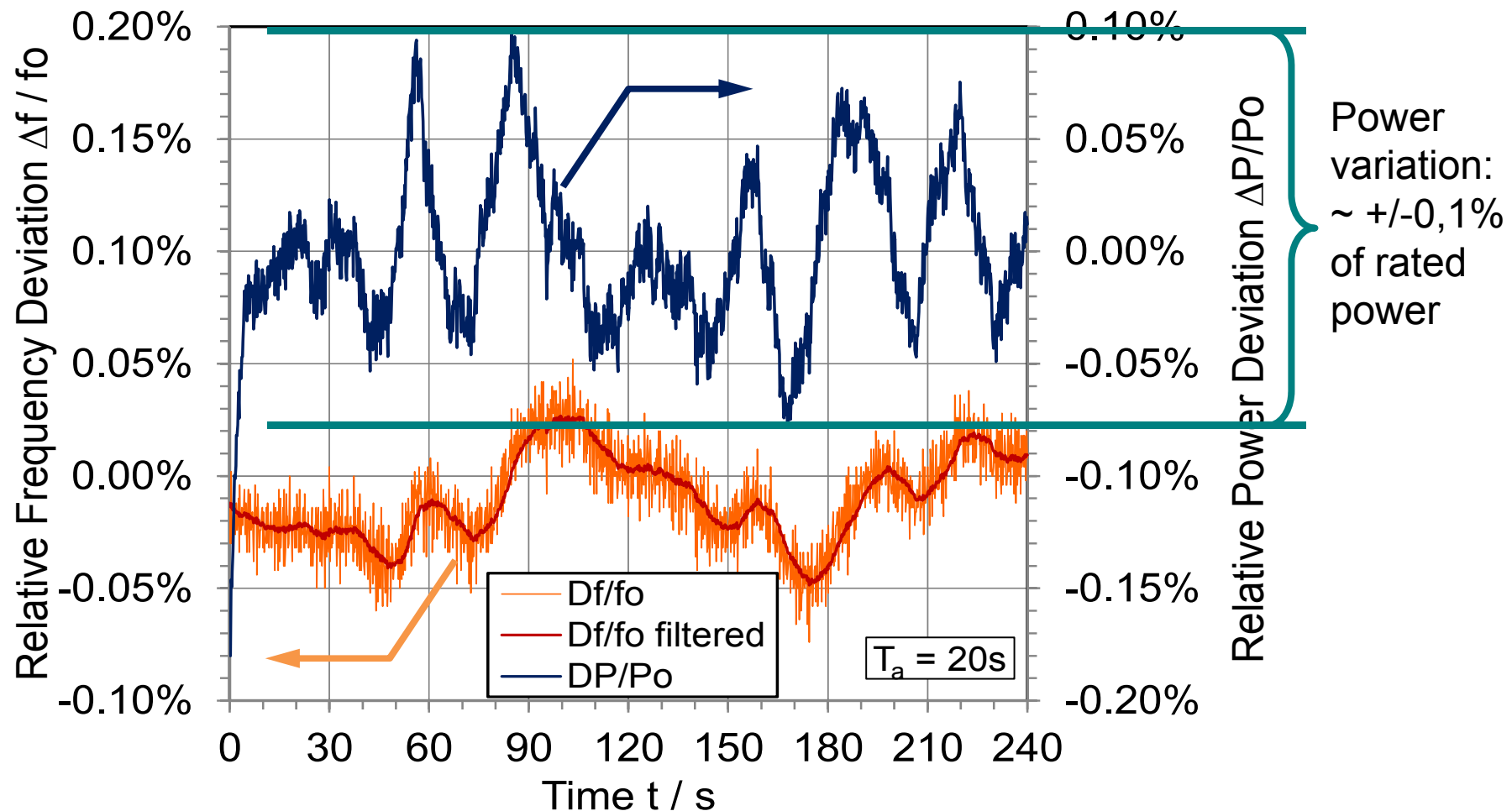




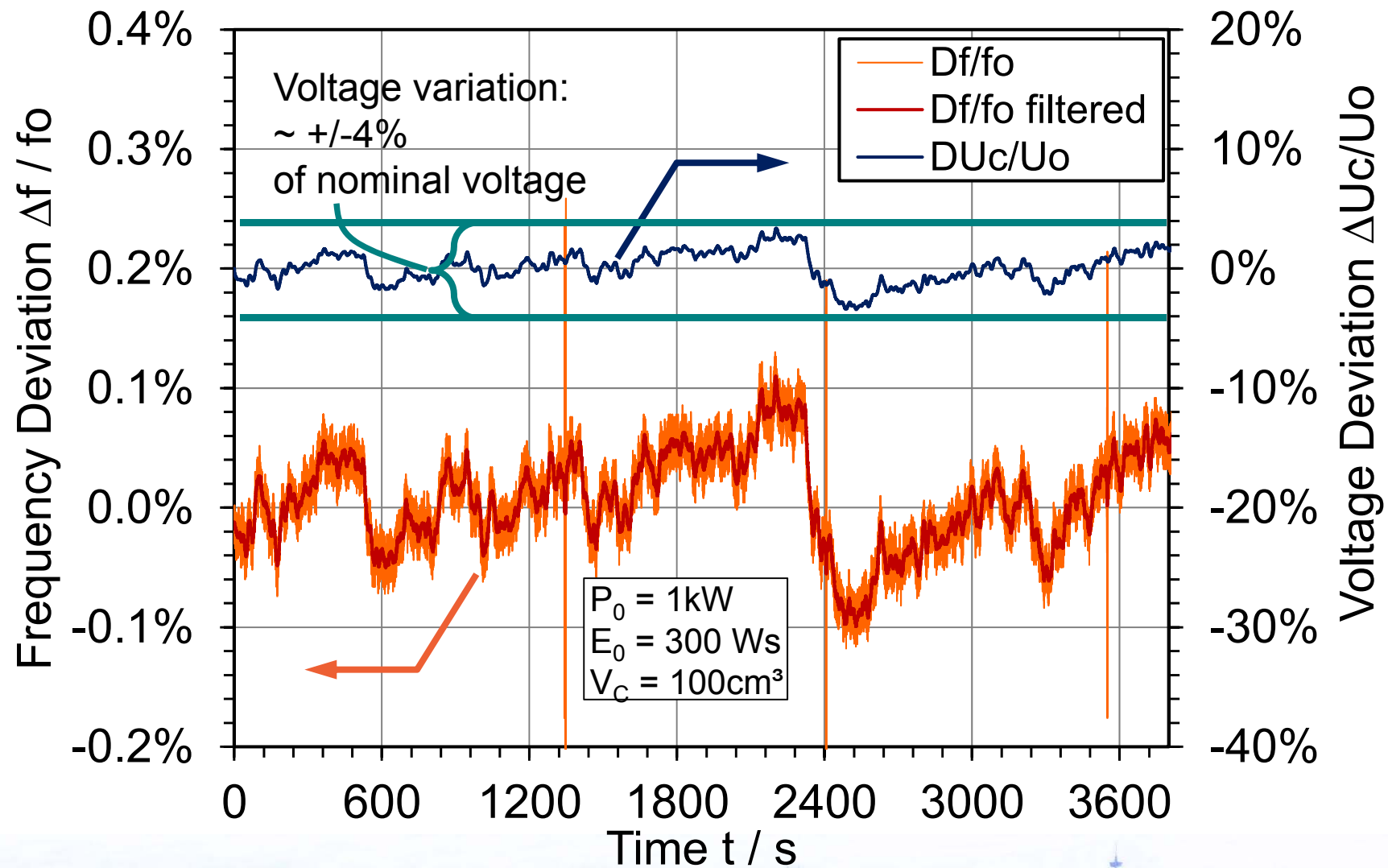
# Needed capacitor size



# Power variation



# Variation of intermediate voltage



# Virtual inertia with power converters

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Use intermediate voltage capacitor:

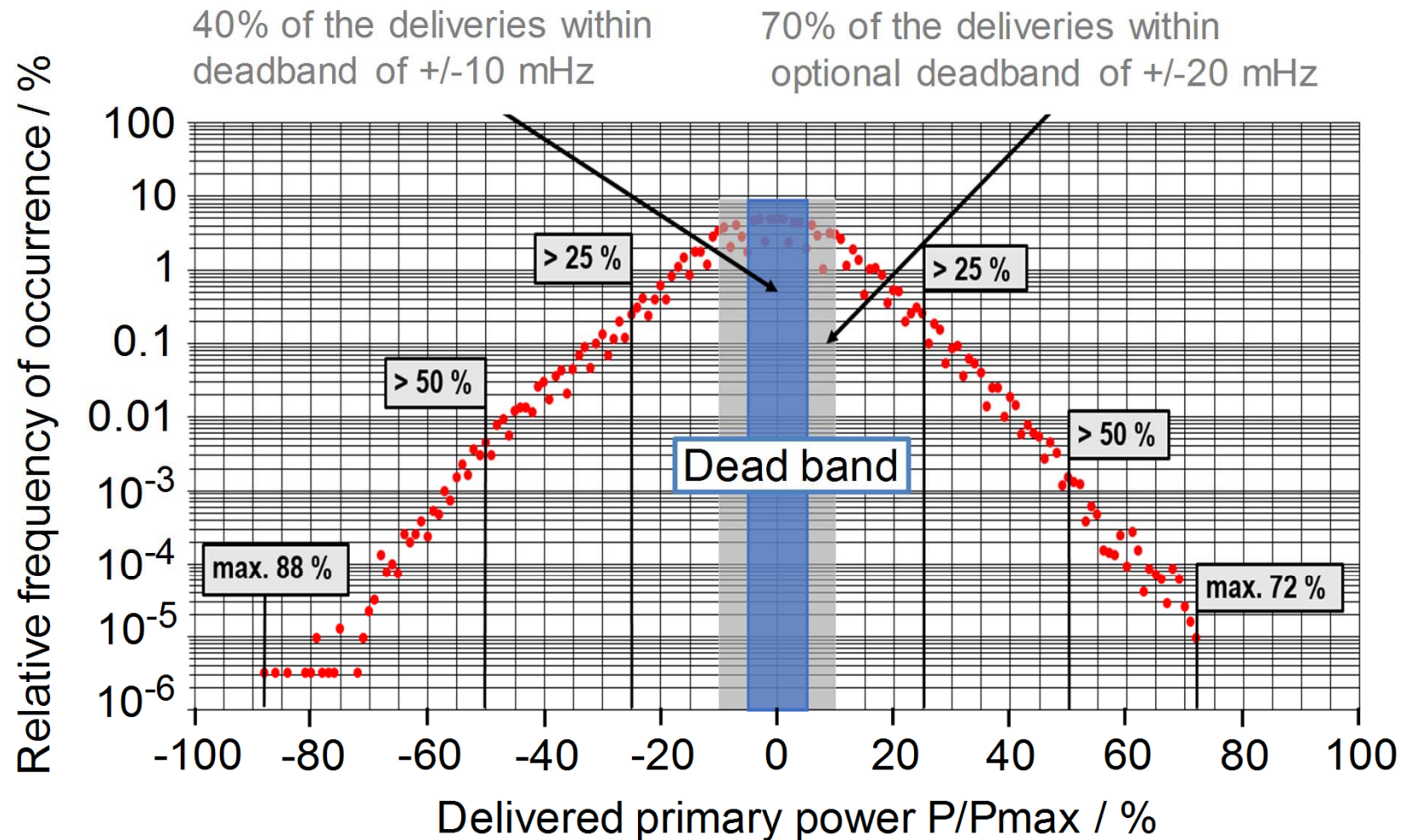
- Typical size is sufficient
- Low additional power ( $\sim \pm 0.1\%$ )
  - No re-dimensioning necessary
- Low voltage ripple ( $\sim \pm 5\%$ )
  - No degradation of elcap



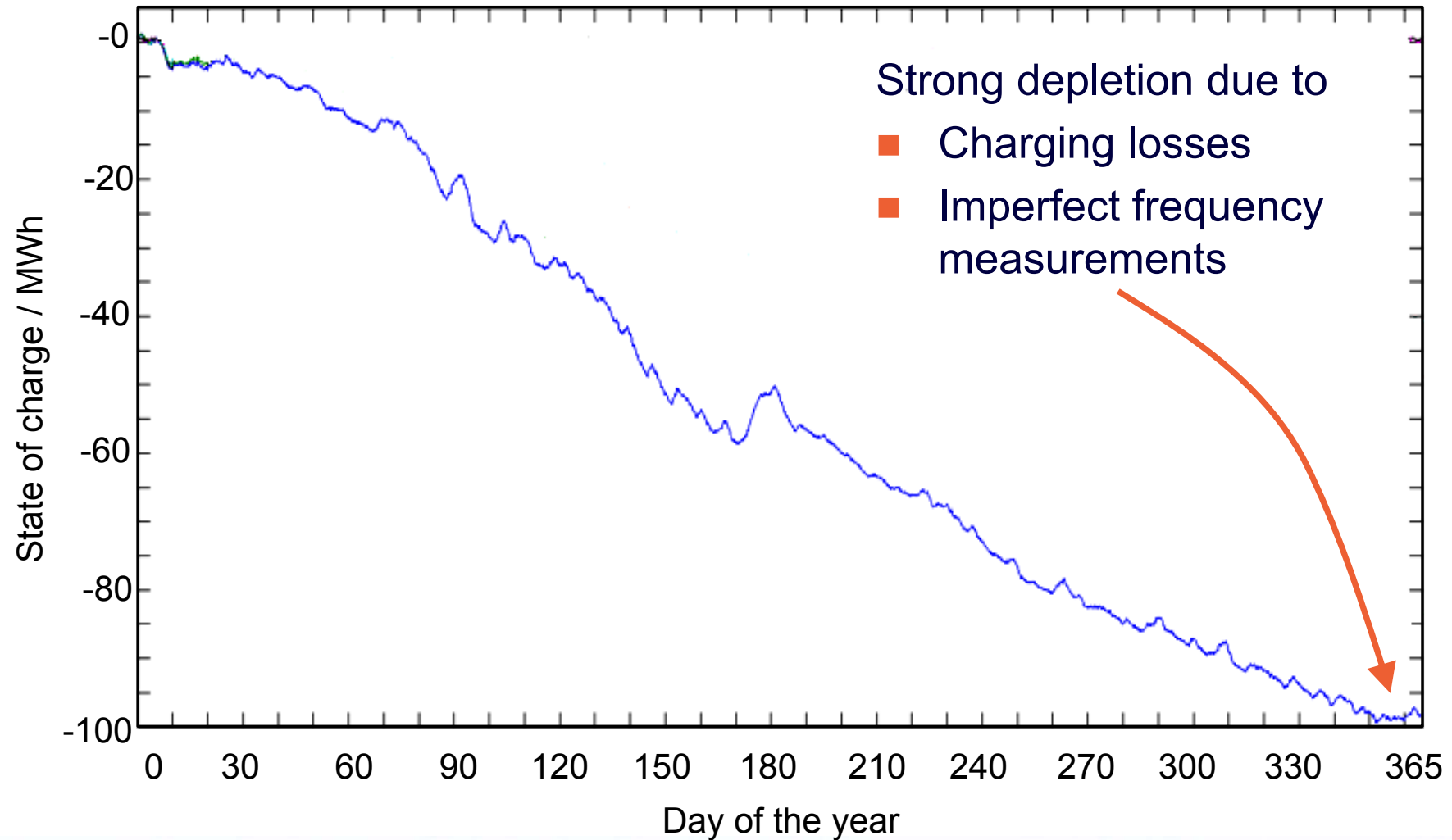
# Primary control with batteries



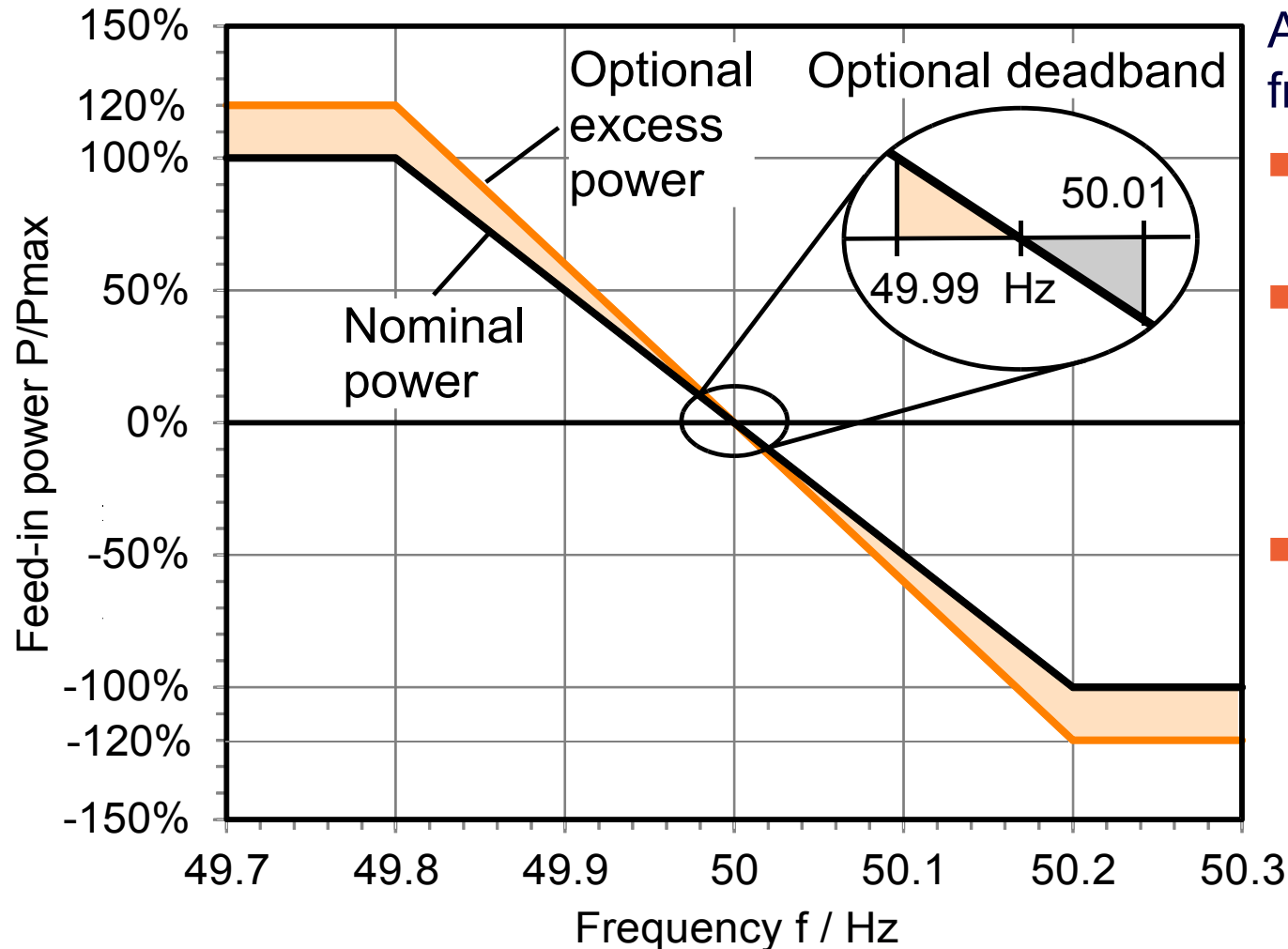
# Occurrence of Primary Control Power in 2013



# State of charge without measures



# Degrees of freedom with Primary Control

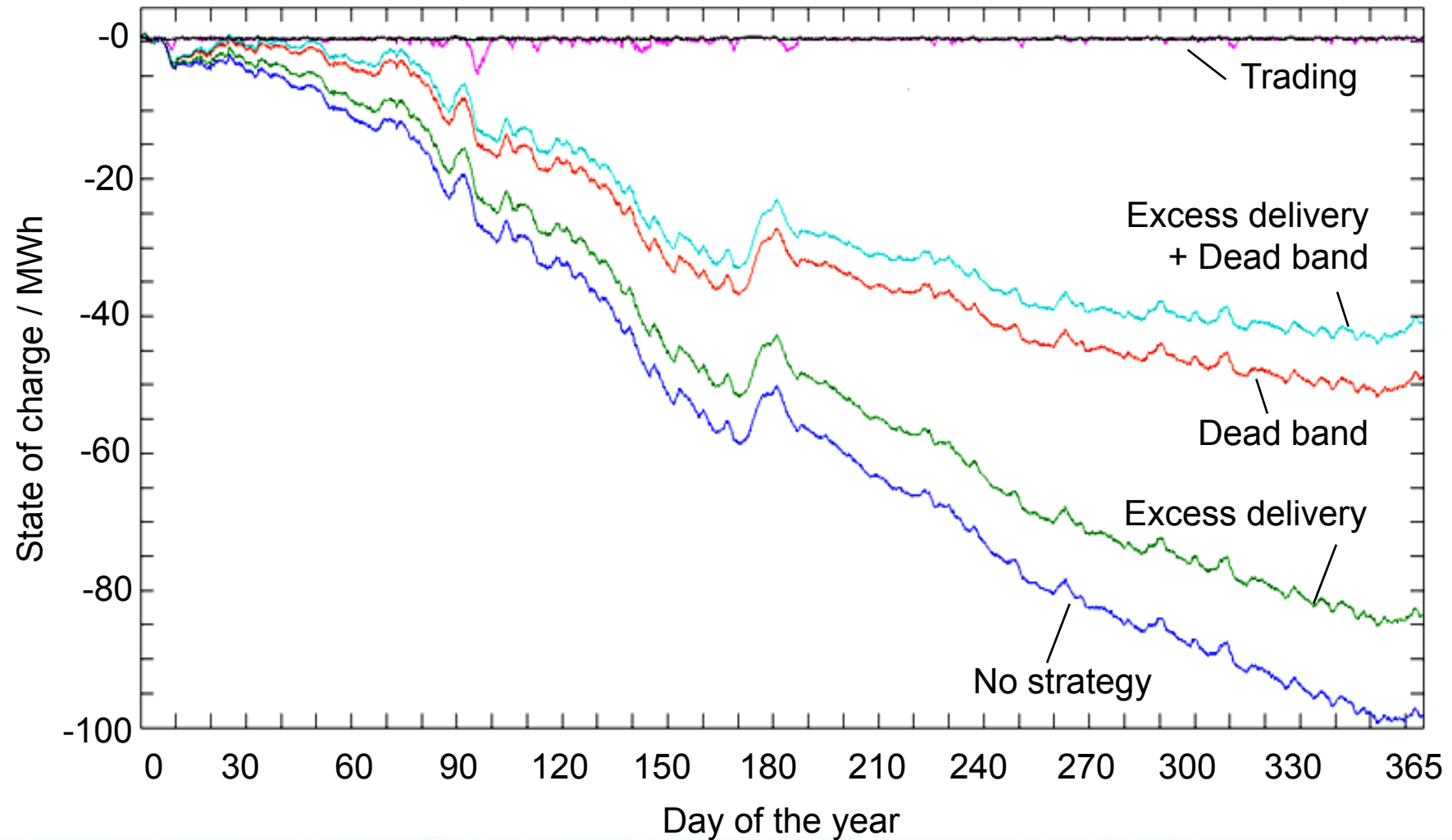


Additional degrees of freedom:

- Delayed reaction: 30s to full power
- Preciseness of frequency measurement: 10 mHz
- Trading of energy



# Effect of applying degrees of freedom

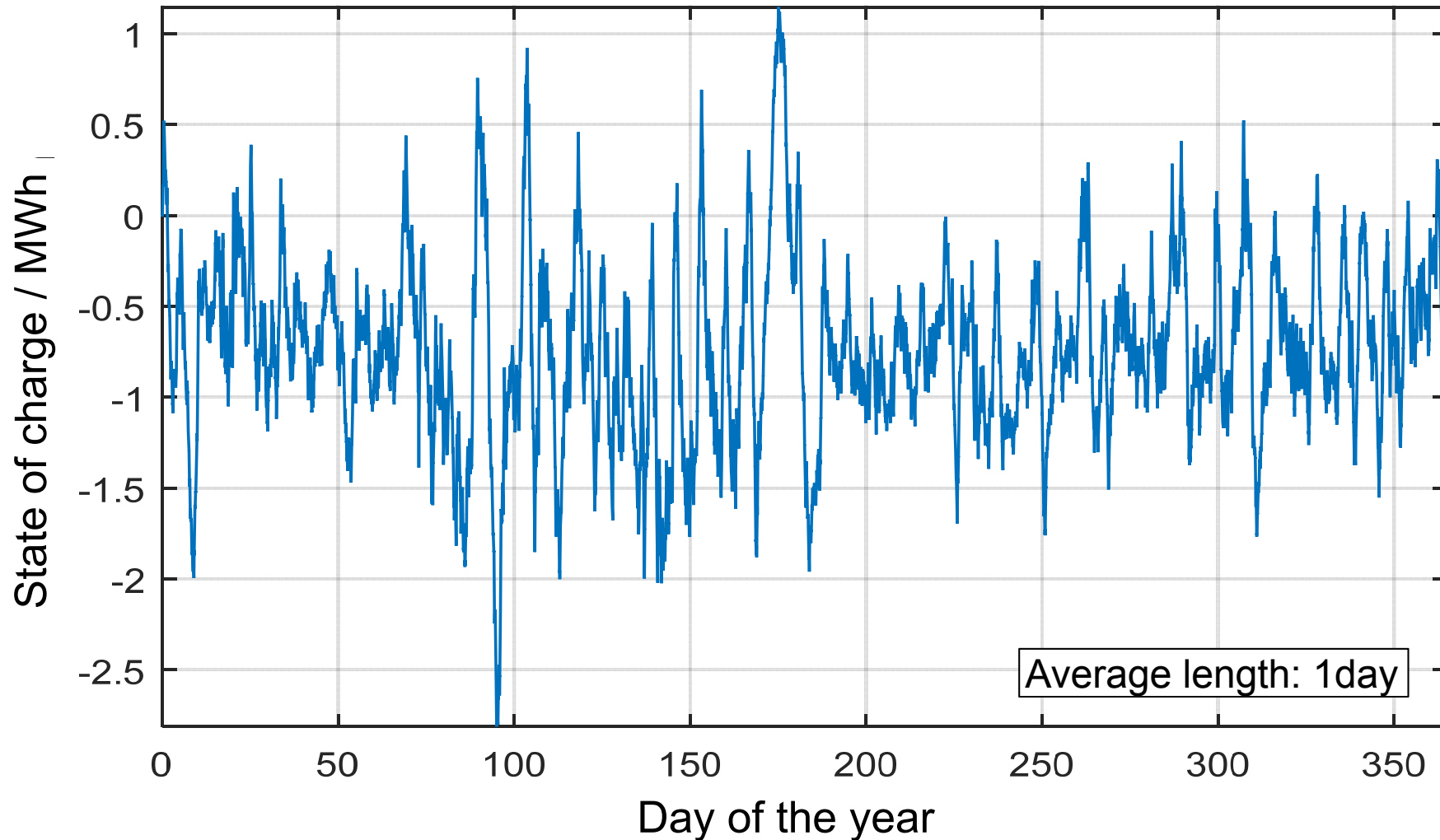


# Preciseness of frequency measurement

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- *Problem:*  
Systematic error of frequency measurement
- *Example:*  
+/-1 mHz -> +/-40 MWh per year
- *Solution:*  
Correction with running average
- *Justification:*  
Deviation from 50.000Hz compensated by power providers (synchronous time correction)

# Application of running average



# Primary control with batteries

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## ■ *Problem:*

Strong depletion due to

- Charging losses
- Imprecise frequency measurements

## ■ *Solution:*

Use degrees of freedom

- Excess delivery
- Deadtime
- Frequency: Averaging
- If anything fails: Energy trading



# Conclusion



# Conclusion

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Grid power control with decentralized sources:

- *Virtual inertia:*  
Use intermediate voltage capacitors  
of power converters
- *Primary control:*  
Use degrees of freedom for batteries

# Contact

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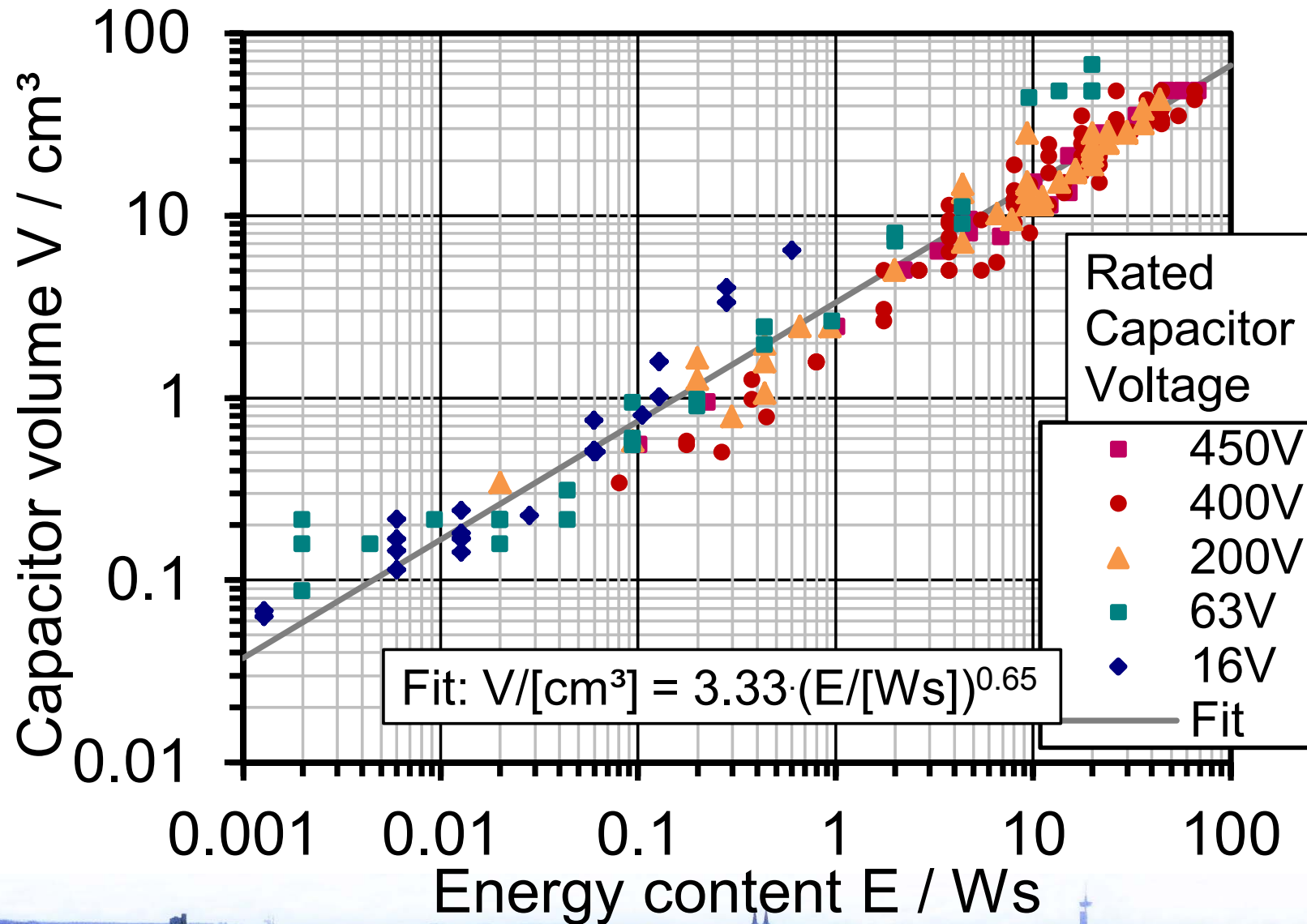


# Appendix





# Size of electrolytic capacitors



# Voltage variations during daily operation

Definition of  
time constant  $T_a$ :

$$\frac{\Delta P}{P_0} = T_a \cdot \frac{d}{dt} \frac{\Delta f}{f}$$

$\Delta P$  = Power step

$P_0$  = Power in the grid

$\Delta f$  = Frequency variation

$f$  = Grid frequency

$C$  = Capacity of the capacitor

$I$  = Current into the capacitor

$U_0$  = Intermediate voltage

$\Delta U_c$  = Voltage variation at capacitor

Power into  
the capacitor:

$$\Delta P = \Delta I \cdot U_0$$

Dependence of  
voltage and current:

$$\Delta U_c(t) = \frac{1}{C} \int \Delta I(t) dt$$

Intermediate  
solution:

$$\Delta U_c(t) = \frac{1}{C} \int \frac{P_0 T_a}{U_0} \cdot \frac{d}{dt} \frac{\Delta f}{f_0} dt$$

Max. energy content  
of capacitor:

$$E_0 = \frac{1}{2} C \cdot U_0^2$$

Solution:

$$\frac{\Delta U_c(t)}{U_0} = T_a \cdot \frac{1}{2} \cdot \frac{P_0}{E_0} \cdot \frac{\Delta f}{f}$$



$$\frac{\Delta U_c(t)}{U_0} \propto \frac{\Delta f}{f}$$

Voltage variation at the capacitor is proportional to the frequency variation